



NSTX

**HHFW (High Harmonic Fast Wave) Eddy Current Analysis
for Antenna**

NSTX-CALC-24-03-00

Jan 10, 2011

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PPPL Calculation Form

Calculation # **NSTXU-CALC-24-03** Revision # **00** WP #, if any **1511**
(ENG-032)

Purpose of Calculation: (Define why the calculation is being performed.)

The model was first built for NSTX to verify the eddy current effect on antenna during plasma disruption. Then it is modified to simulate plasma disruption case for NSTX upgrade. Only mid-plane disruption is considered and VDE is not included.

Plasma is modeled to be torus shape and current disappears linearly in 1 ms. Then a background field with Bvertical and Btoroidal is added to calculate the Lorenz force of the induced eddy current in the components. The force data was transferred to the structural model to calculate stress in antenna and Faraday cage and loads on the fixtures.

References (List any source of design information including computer program titles and revision levels.)

Assumptions (Identify all assumptions made as part of this calculation.)

Plasma is modeled to be torus shape which parameters are from NSTX. NSTX upgrade has larger plasma radius but not reflected in this model. Also centerstack is not included.

Background field data are given and added to the model by specify the vector potentials.

The electrical feedthroughs and some structural fixations (e.g. ceramic plug assembly) are too complicated and thus simplified in the model.

Calculation (Calculation is either documented here or attached)

See the attached document.

Conclusion (Specify whether or not the purpose of the calculation was accomplished.)

For NSTX the typical disruption time is 9 ms but the simulation uses 1 ms, very conservative. Stesses in the antenna and Faraday cage are low and they are safe enough.

With NSTX upgrade, displacement of antenna is within 0.6 mm and maximal Von Mises stress is in the strips of Faraday cage, 155 MPa (22.5ksi), within allowable. Loads in the fixtures are extracted and will be analyzed by Robert Ellis.

Bdot data at different positions are calculated to compare with other disruption simulation results.

Cognizant Engineer's printed name, signature, and date

I have reviewed this calculation and, to my professional satisfaction, it is properly performed and correct.

Checker's printed name, signature, and date

Executive Summary

A model including plasma, 4 antennas and vacuum vessel was built to simulate the eddy current and resulting stress in antenna during plasma disruption. The model of vacuum vessel and antenna is imported from CAD model but with adequate modifications. The plasma is modeled as a torus according to the parameters of NSTX. 1ms disruption time is used to obtain more conservative result. Only midplane disruption is considered and VDE is not included.

For NSTX, the electromagnetic model is run first to calculate eddy current. Then, use the same model, reading the eddy current in to run a steady state but with two external magnetic field $B_{\text{poroidal}}=0.4\text{T}$ and $B_{\text{toroidal}}=0.4\text{T}$ added, to calculate the force. Finally a structural model (removing the air element and adding some structural fixation) is run to calculate the stress.

This model is then modified to have higher plasma current 2MA and run again for NSTX upgrade to obtain B_{dot} to compare results from Opera. Background field of $B_{\text{poroidal}}=0.65\text{T}$ and $B_{\text{toroidal}}=0.56\text{T}$ is added to calculate Lorenz force at 1 ms (i.e. end of disruption). The force data was transferred to the structural model to calculate stress in antenna and Faraday cage and loads on the fixtures.

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Modeling

This is a transient analysis. The model of vacuum vessel and antenna is imported from CAD model but with adequate modifications. Only 1/12 (30°) of vacuum vessel and 4 antennas (Fig.1) are included. In this way, it assumes the whole model is by repeating this portion 12 times. But in real machine, the vacuum vessel is not perfectly cyclic and antennas are not distributed along the whole 360°. To save space and time, these differences are neglected. The materials are listed in Fig. 2. Some parts are made of composite material. Equivalent resistivity is calculated for them according to the dimension and resistivity of pure material and then applied to the parts. The electrical feedthroughs and some structural fixations (i.e. ceramic plug assembly) contain stainless steel flanges, conductors, bellows and ceramic insulation which are too complicated and thus simplified in the model (Fig. 3).

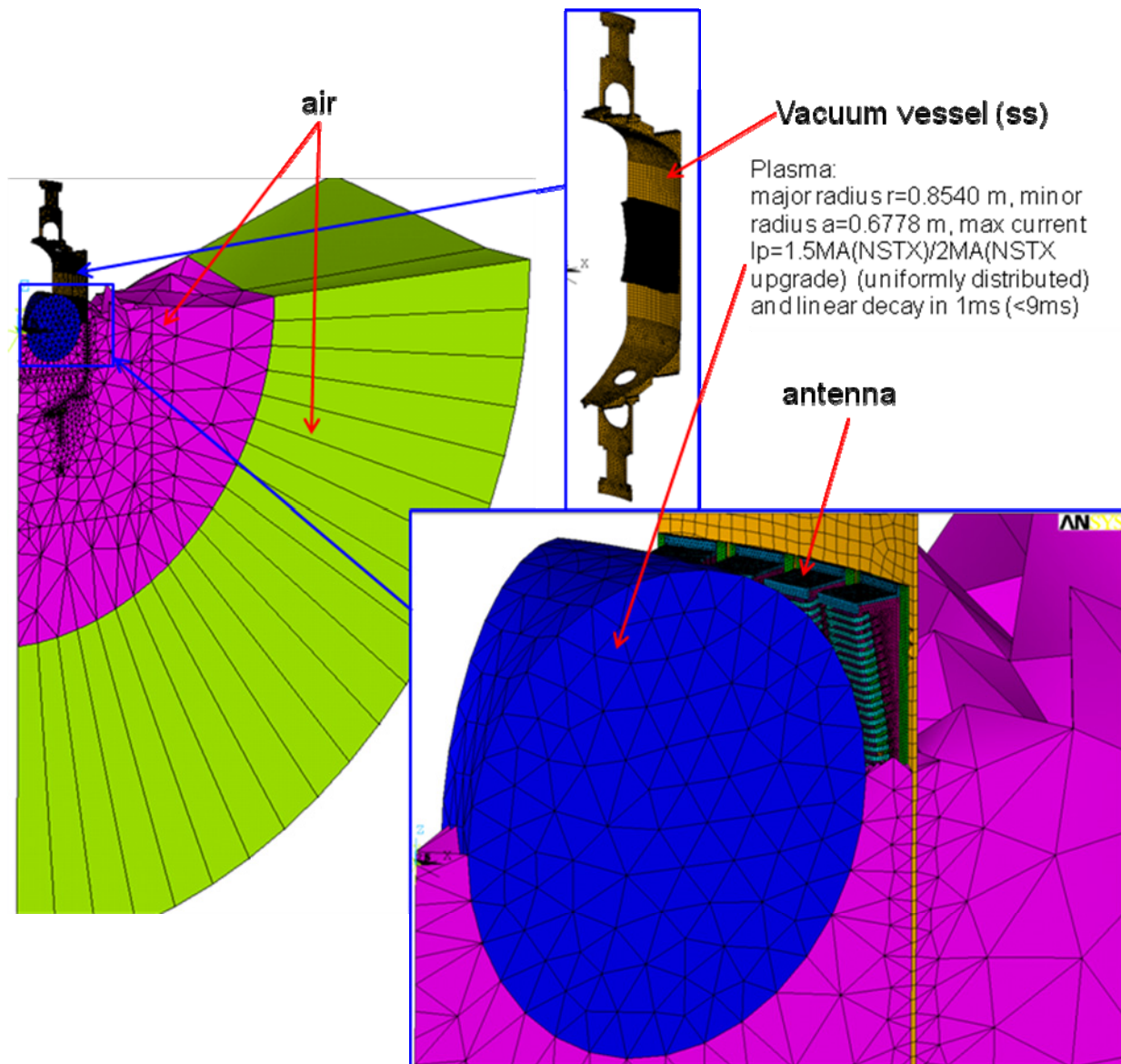


Figure 1: Electro-magnetic model.

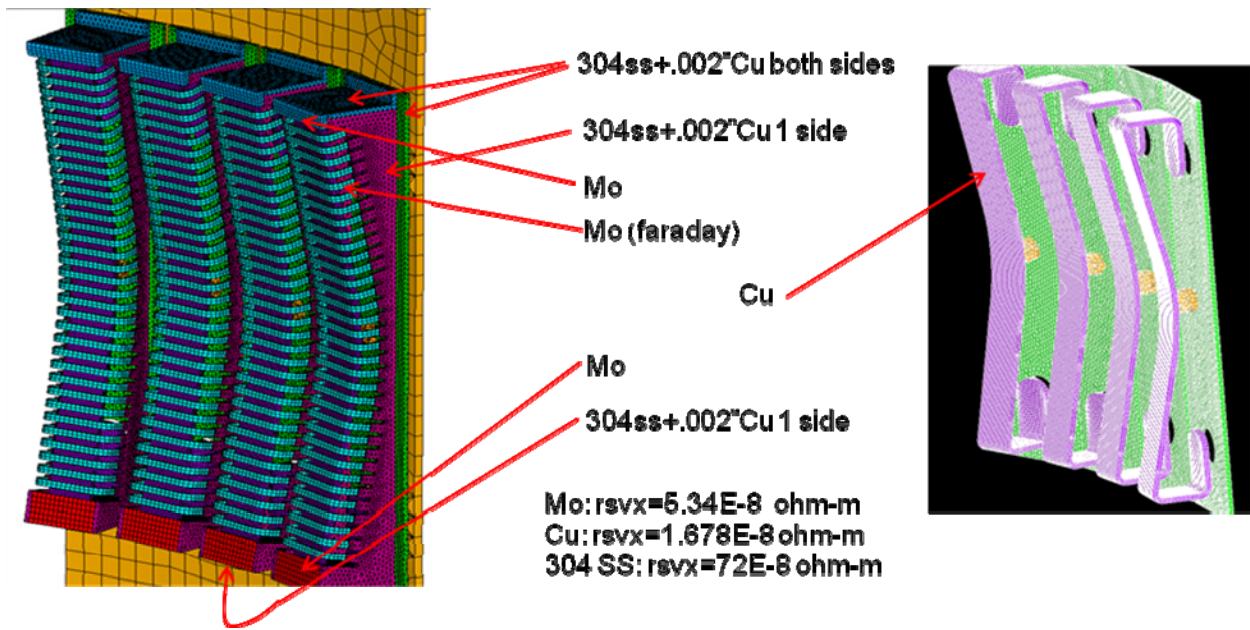


Figure 2: Materials of antenna.

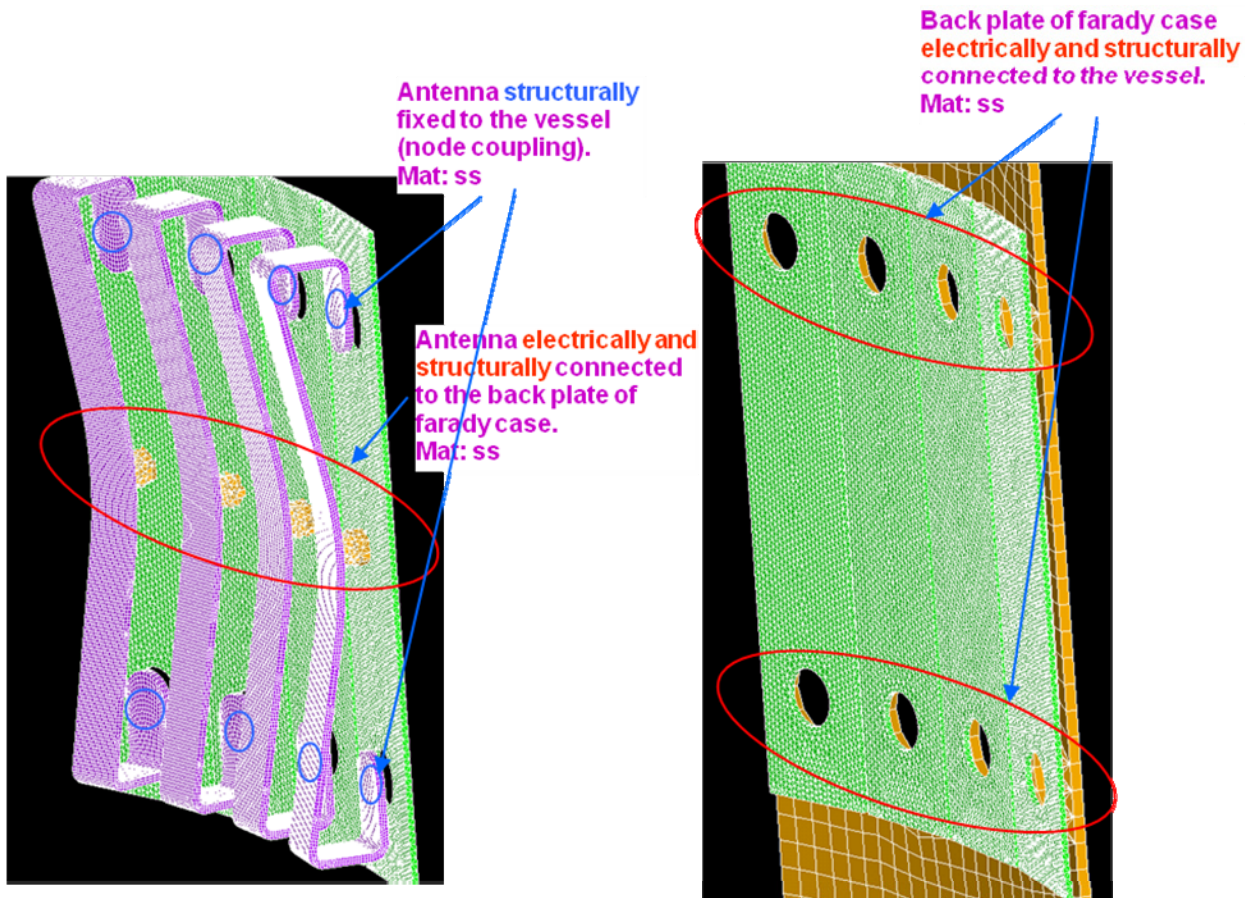


Figure 3: Some electrical and structural connections are simplified in the model.

The plasma is modeled as a torus with major radius of 0.8540m, minor radius of 0.6778m, maximal current of 1.5MA (uniformly distributed) and linear decay in 9ms (Fig. 1), which is

according to the parameters of NSTX. In this model, 1ms disruption time is used to obtain more conservative result. Only midplane disruption is considered and VDE is not included. This model is used to run the NSTX upgrade disruption later to obtain Bdot to compare with other analysis, which will be described in the following chapters of this document.

Results for NSTX

For NSTX, according to previous analysis, the plasma disrupts in 9ms. I used 1ms to obtain conservative result. First the electromagnetic model is run to calculate eddy current. Then, use the same model, reading the eddy current in to run a steady state but with two external magnetic field $B_{\text{poroidal}}=0.4\text{T}$ and $B_{\text{toroidal}}=0.4\text{T}$ added, to calculate the force. Finally a structural model (removing the air element and adding some structural fixation) is run to calculate the stress.

Fig. 4 shows the eddy current pattern in the antenna. Fig. 5 and Fig. 6 show the Von Mises stress in Pa. The ends of antenna are fixed to vessel but I didn't model the fixture, only couple some nodes together, which causes the high stress (red spots in the figure). Since the stresses are low enough, it won't be necessary for further analysis. Eddy current pattern in vessel is plotted in Fig. 7. Eddy current mainly generates at the cylinder and flows around the holes and some high current density around the edge of the hole can be easily seen. This is because I defeature the ports and leave the holes. This analysis aims at the antenna. This simplification should not be a problem. But if analyze the vessel, port extension and cover should be kept and eddy current will flow to them and distribute more uniformly than this figure shows. Fig. 8 shows the Von Mises stress in vessel. The high stress points are the places connecting to the antenna and back plate of Faraday cage by directly coupling nodes. Since these stresses are low enough and no need for further analysis.

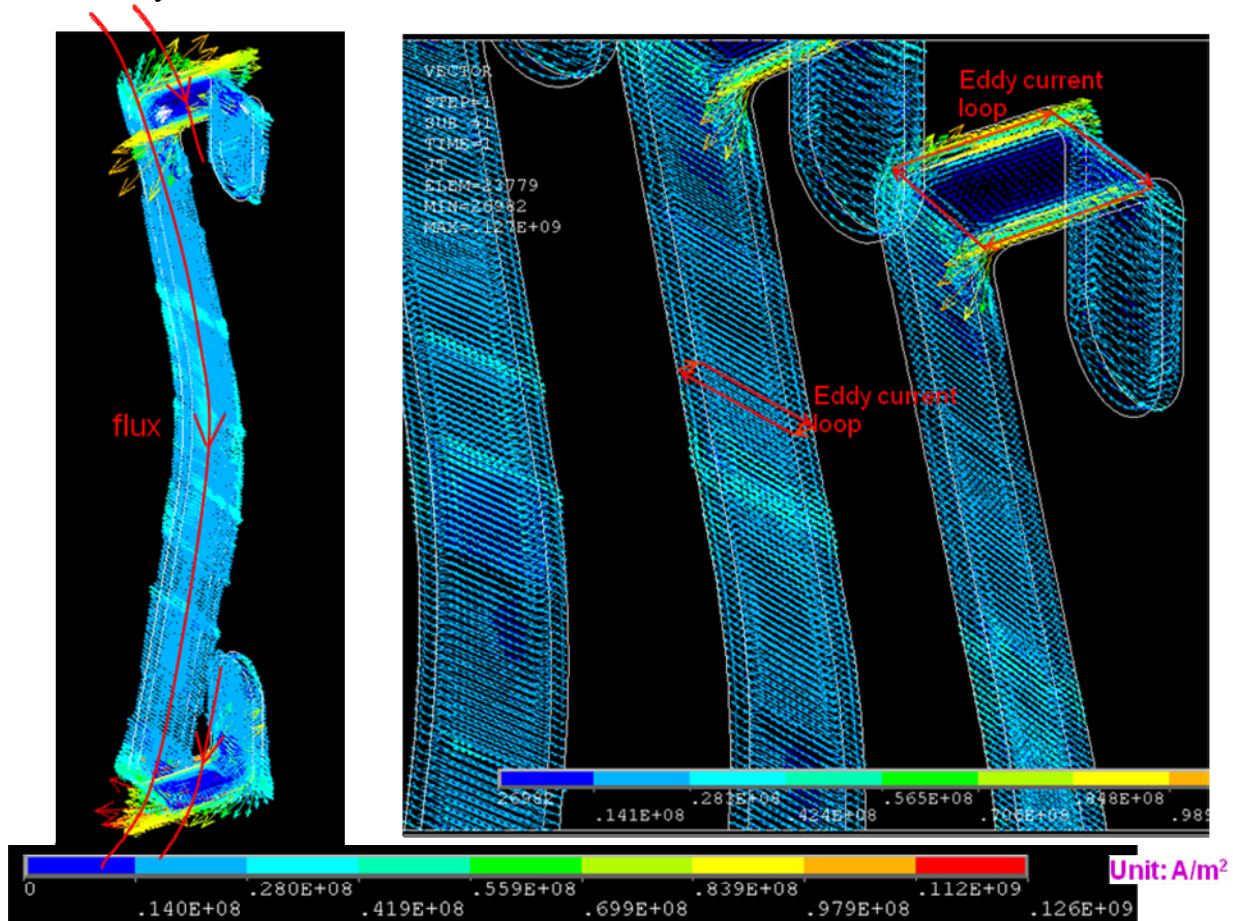


Figure 4: Eddy current pattern of antenna at 1ms (A/m^2).

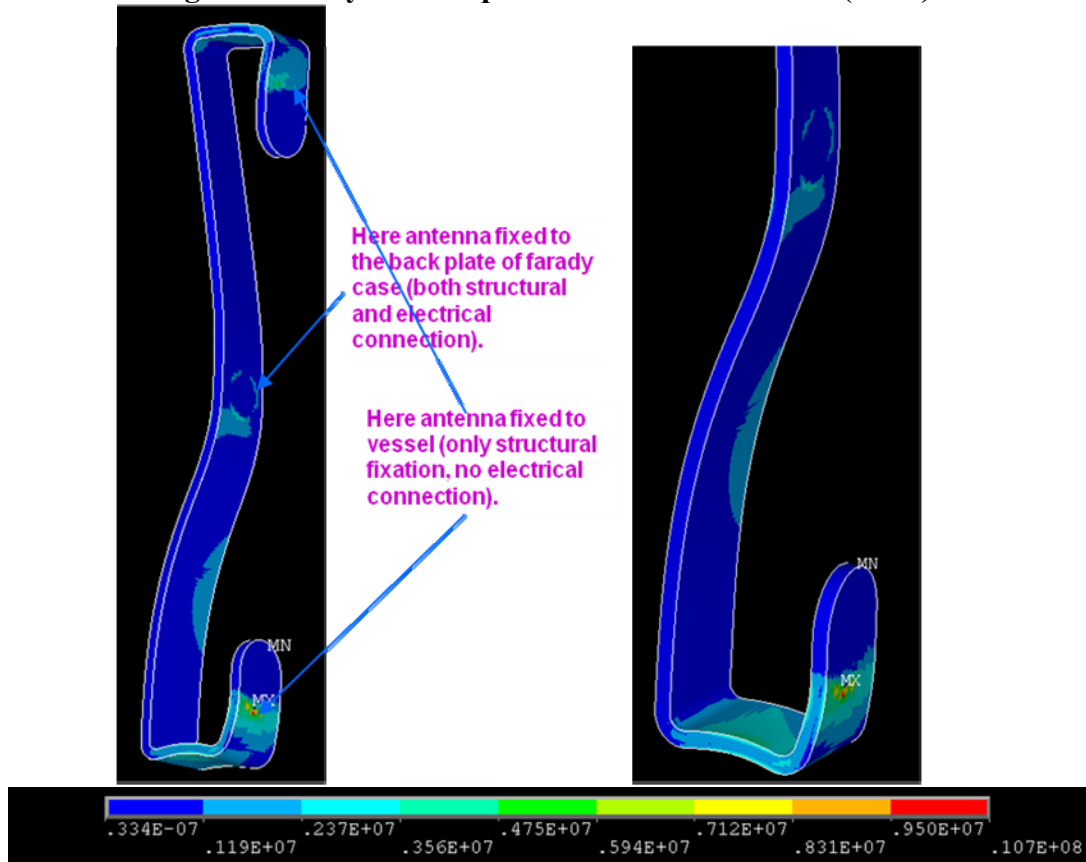


Figure 5: Von Mises stress in the antenna (Pa).

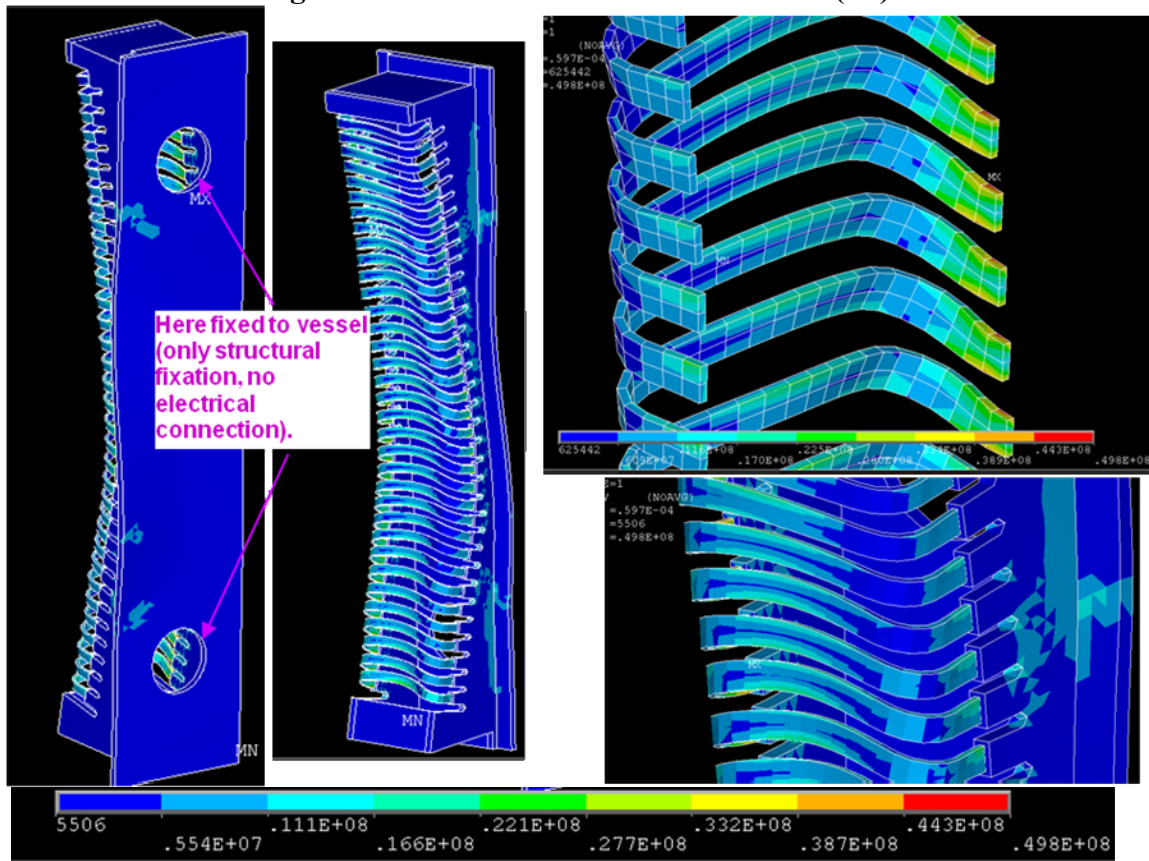


Figure 6: Von Mises stress in Faraday shield (Pa).

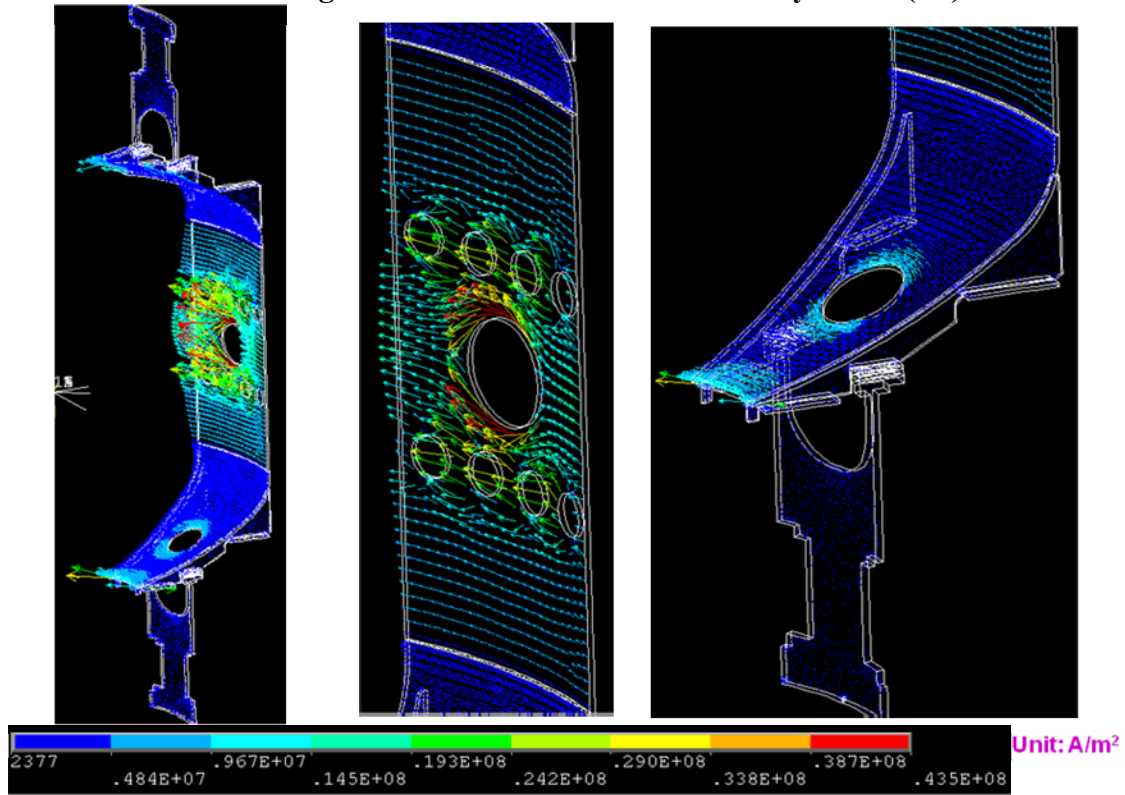


Figure 7: At 1ms, eddy current pattern in vessel (A/m²).

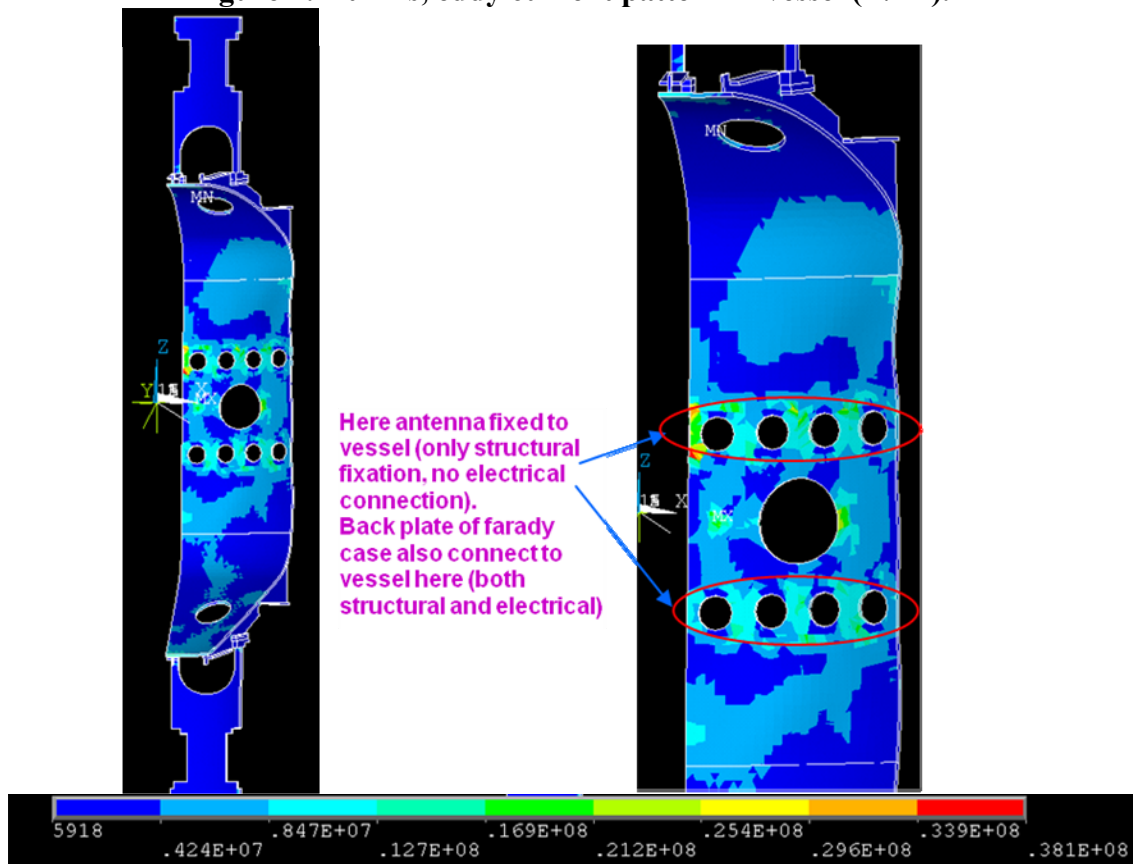


Figure 8: Von Mises stress in vessel (Pa).

Results for NSTX upgrade

Then the electromagnetic model is modified to have 2MA plasma current uniformly distributed and linearly decay in 1ms to simulate the disruption of NSTX upgrade. But NSTX upgrade has bigger plasma major radius which is neglected in the model just to simplify the modifications. This analysis is mainly to calculate the Bdot to compare with other's Bdot result from Opera. I arbitrarily select 9 positions (Fig. 9) to output the B and calculate Bdot using excel. The Bdot data are listed in Table 1 to 3 and plotted in Fig. 10 to 12.

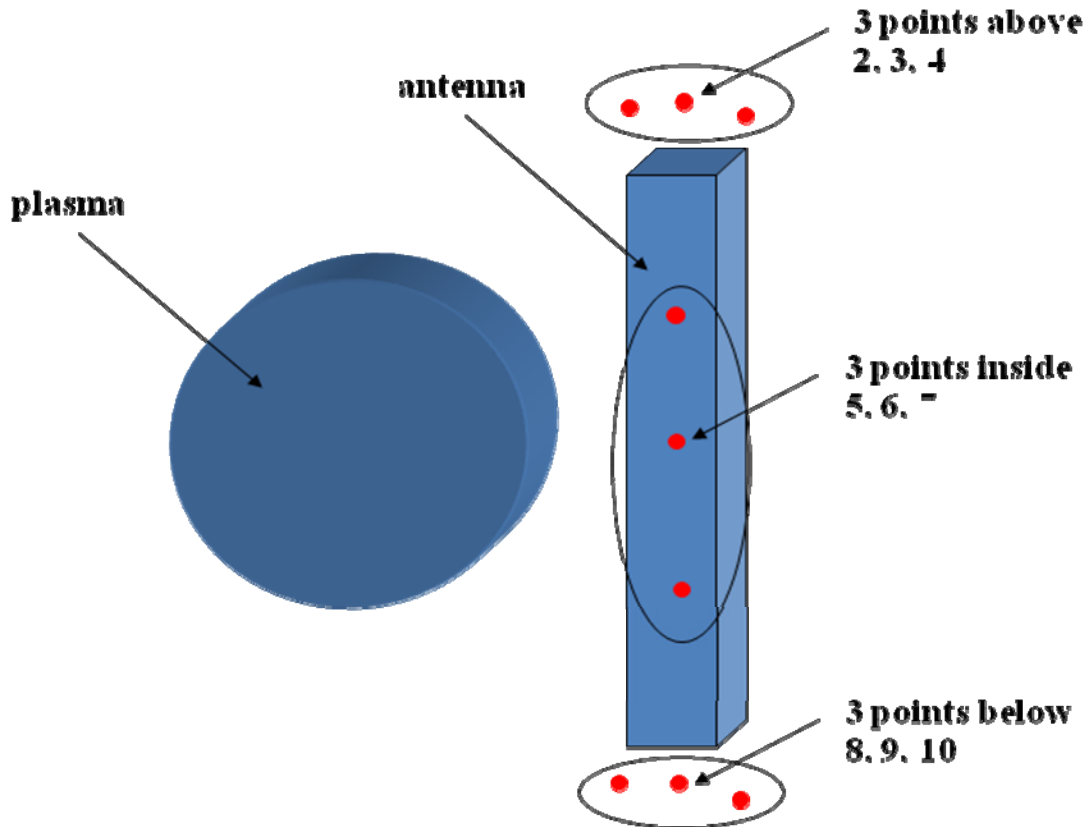


Figure 9: Nine positions are arbitrarily chosen to calculate Bdot.

Table I: In cylindrical coordinate, radial component of B and calculated B_{r_dot} (T/s).

time (s)	above antenna			inside antenna			below antenna		
	Br_2	Br_3	Br_4	Br_5	Br_6	Br_7	Br_8	Br_9	Br_10
1.00E-03	0.158781	0.122672	0.114901	0.077401	0.003396	-0.076580	-0.152201	-0.114211	-0.100220
1.09E-03	0.154130	0.121410	0.114789	0.077872	0.004284	-0.077812	-0.147669	-0.114733	-0.099927
1.18E-03	0.148276	0.119081	0.113384	0.076921	0.004582	-0.076988	-0.141955	-0.113877	-0.098975
1.27E-03	0.141930	0.116366	0.111579	0.075383	0.004762	-0.075482	-0.135768	-0.112542	-0.097836
1.36E-03	0.135126	0.113312	0.109440	0.073398	0.004892	-0.073513	-0.129146	-0.110808	-0.096542
1.45E-03	0.127969	0.109973	0.107011	0.070986	0.004900	-0.071037	-0.122190	-0.108722	-0.095076
1.55E-03	0.120478	0.106386	0.104328	0.068139	0.004887	-0.068100	-0.114915	-0.106323	-0.093468
1.64E-03	0.112704	0.102554	0.101401	0.065016	0.004840	-0.064773	-0.107368	-0.103633	-0.091699
1.73E-03	0.104675	0.098526	0.098270	0.061522	0.004692	-0.061095	-0.099579	-0.100690	-0.089812
1.82E-03	0.096419	0.094297	0.094938	0.057706	0.004558	-0.057055	-0.091575	-0.097509	-0.087774
1.91E-03	0.087955	0.089902	0.091437	0.053685	0.004387	-0.052759	-0.083372	-0.094122	-0.085606
2.00E-03	0.079306	0.085319	0.087764	0.049368	0.004191	-0.048194	-0.074994	-0.090540	-0.083334

Br dot (T/s) in cylindrical coordinate									
-51.17	-13.88	-1.23	5.18	9.77	-13.56	49.86	-5.74	3.23	
-64.40	-25.63	-15.46	-10.46	3.28	9.07	62.85	9.41	10.48	
-69.81	-29.87	-19.86	-16.92	1.98	16.56	68.06	14.68	12.53	
-74.84	-33.60	-23.53	-21.84	1.43	21.66	72.86	19.08	14.23	
-78.74	-36.74	-26.72	-26.54	0.08	27.25	76.53	22.94	16.13	
-82.32	-39.42	-29.48	-31.28	-0.13	32.27	79.94	26.36	17.67	
-85.52	-42.15	-32.20	-34.36	-0.52	36.60	83.02	29.60	19.46	
-88.33	-44.32	-34.44	-38.43	-1.63	40.47	85.69	32.37	20.76	
-90.82	-46.52	-36.66	-41.98	-1.47	44.44	88.05	34.99	22.41	
-93.12	-48.36	-38.51	-44.23	-1.88	47.26	90.24	37.26	23.85	
-95.15	-50.42	-40.41	-47.49	-2.15	50.23	92.16	39.41	24.99	

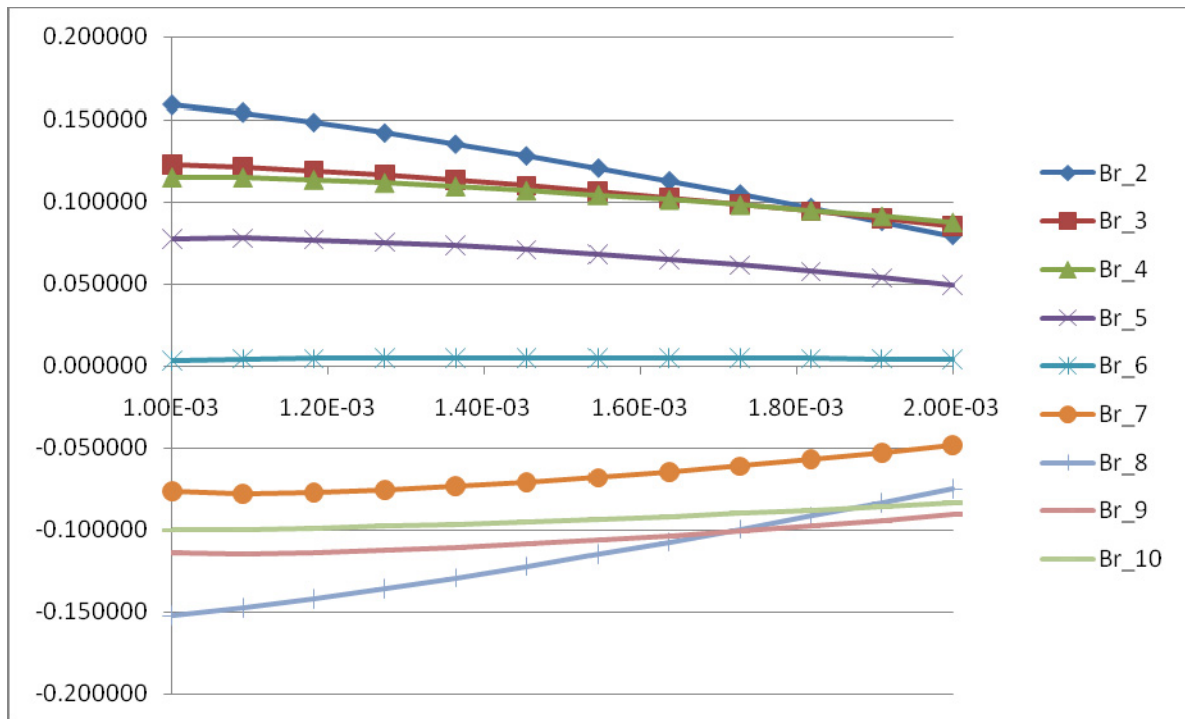


Figure 10: History plot of Br (x axis—Time(s), y axis—B (Tesla), Plasma disrupts from 1ms to 2ms).

Table II: Toroidal component of B with time and calculated Bt_dot (T/s).

time (s)	above antenna			inside antenna			below antenna		
	Bt_2	Bt_3	Bt_4	Bt_5	Bt_6	Bt_7	Bt_8	Bt_9	Bt_10
1.00E-03	-0.135555	-0.106353	-0.102805	-0.067603	-0.000301	0.067287	0.137897	0.100475	0.088238
1.09E-03	-0.131577	-0.104766	-0.102021	-0.066989	-0.000226	0.066395	0.133324	0.099643	0.087514
1.18E-03	-0.126834	-0.102699	-0.100755	-0.067303	-0.000263	0.066620	0.128053	0.098397	0.086774
1.27E-03	-0.121690	-0.100357	-0.099169	-0.067632	-0.000272	0.066729	0.122402	0.096867	0.085922
1.36E-03	-0.116143	-0.097731	-0.097245	-0.067789	-0.000268	0.066601	0.116359	0.095013	0.084908
1.45E-03	-0.110300	-0.094886	-0.095076	-0.067827	-0.000236	0.066305	0.110041	0.092938	0.083805
1.55E-03	-0.104168	-0.091818	-0.092643	-0.067676	-0.000198	0.065804	0.103435	0.090605	0.082518
1.64E-03	-0.097819	-0.088595	-0.090032	-0.067316	-0.000117	0.065088	0.096623	0.088105	0.081161
1.73E-03	-0.091235	-0.085185	-0.087207	-0.066829	0.000015	0.064161	0.089586	0.085388	0.079653
1.82E-03	-0.084477	-0.081641	-0.084226	-0.066111	0.000105	0.063093	0.082382	0.082525	0.078062
1.91E-03	-0.077530	-0.077936	-0.081060	-0.065214	0.000159	0.061874	0.074993	0.079482	0.076366
2.00E-03	-0.070436	-0.074110	-0.077758	-0.064207	0.000205	0.060488	0.067466	0.076305	0.074543

Bt dot (T/s) in cylindrical coordinate									
43.76	17.46	8.63	6.75	0.82	-9.80	-50.30	-9.15	-7.97	
52.18	22.74	13.92	-3.45	-0.41	2.47	-57.99	-13.71	-8.14	
56.59	25.76	17.45	-3.63	-0.09	1.20	-62.18	-16.83	-9.37	
61.02	28.90	21.17	-1.72	0.04	-1.41	-66.47	-20.40	-11.15	
64.28	31.29	23.86	-0.42	0.35	-3.25	-69.51	-22.82	-12.14	
67.39	33.72	26.74	1.66	0.42	-5.51	-72.59	-25.64	-14.14	
69.85	35.46	28.72	3.96	0.89	-7.87	-74.94	-27.50	-14.93	
72.44	37.51	31.09	5.36	1.45	-10.20	-77.41	-29.89	-16.59	
74.35	38.99	32.79	7.90	0.99	-11.75	-79.26	-31.50	-17.51	
76.42	40.77	34.82	9.86	0.59	-13.41	-81.28	-33.48	-18.65	
78.04	42.09	36.33	11.08	0.51	-15.25	-82.81	-34.95	-20.05	

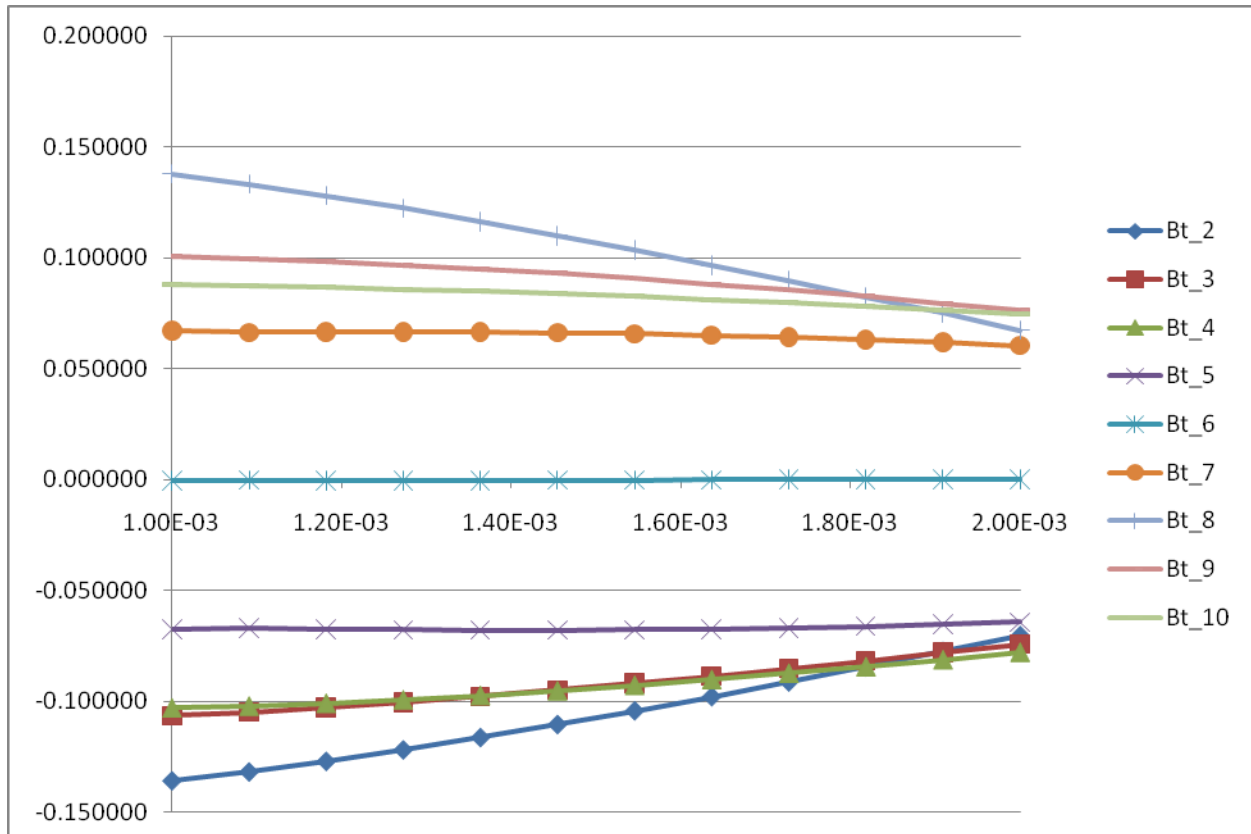


Figure 11: History plot of Bt (x axis—Time(s), y axis—B (Tesla), Plasma disrupts from 1ms to 2ms).

Table III: Poloidal component of B with time and calculated Bz_dot (T/s).

time (s)	above antenna			inside antenna			below antenna		
	BZ_2	BZ_3	BZ_4	BZ_5	BZ_6	BZ_7	BZ_8	BZ_9	BZ_10
1.00E-03	-6.43E-02	-4.53E-02	-5.10E-02	-0.153989	-0.18615	-0.158143	-5.65E-02	-6.59E-02	-5.47E-02
1.09E-03	-4.03E-02	-2.75E-02	-3.30E-02	-0.151737	-0.183004	-0.15682	-3.33E-02	-4.72E-02	-3.76E-02
1.18E-03	-1.66E-02	-9.03E-03	-1.41E-02	-0.145861	-0.175897	-0.15132	-1.04E-02	-2.74E-02	-1.94E-02
1.27E-03	7.06E-03	9.86E-03	5.22E-03	-0.135675	-0.165017	-0.1415	1.26E-02	-7.03E-03	-6.26E-04
1.36E-03	3.08E-02	2.92E-02	2.50E-02	-0.121633	-0.150762	-0.127905	3.56E-02	1.39E-02	1.87E-02
1.45E-03	5.46E-02	4.87E-02	4.51E-02	-0.104215	-0.134021	-0.111012	5.87E-02	3.53E-02	3.84E-02
1.55E-03	7.84E-02	6.86E-02	6.55E-02	-8.39E-02	-0.115067	-9.13E-02	8.17E-02	5.71E-02	5.85E-02
1.64E-03	0.102127	8.86E-02	8.61E-02	-6.11E-02	-9.44E-02	-6.92E-02	0.10475	7.91E-02	7.89E-02
1.73E-03	0.12588	0.108719	0.106917	-3.63E-02	-7.21E-02	-4.50E-02	0.12777	0.101344	9.95E-02
1.82E-03	0.149592	0.128977	0.127823	-9.53E-03	-4.86E-02	-1.90E-02	0.150742	0.123768	0.120255
1.91E-03	0.173284	0.14935	0.148872	1.87E-02	-2.40E-02	8.49E-03	0.1737	0.146364	0.141214
2.00E-03	0.196926	0.169782	0.169984	4.83E-02	1.57E-03	3.73E-02	0.196604	0.169059	0.162282

Bz dot (T/s) in cylindrical coordinate								
263.90	195.77	198.37	24.77	34.61	14.55	255.14	205.85	187.70
260.65	203.44	207.71	64.64	78.18	60.51	252.53	217.48	200.33
260.88	207.86	212.75	112.06	119.69	108.03	252.81	224.26	206.59
261.37	212.39	217.85	154.48	156.82	149.56	253.34	230.77	213.04
261.45	215.31	221.25	191.62	184.17	185.84	253.38	235.16	216.57
261.36	217.91	224.24	223.19	208.29	216.62	253.30	239.01	220.76
261.32	219.90	226.52	250.63	226.87	243.39	253.23	242.19	224.03
261.31	221.81	228.68	273.54	245.70	266.31	253.25	244.85	226.50
260.86	222.86	229.99	294.02	258.68	285.85	252.72	246.69	228.69
260.64	224.13	231.56	311.09	270.91	302.23	252.56	248.58	230.57
260.09	224.77	232.26	325.13	280.99	316.41	251.97	249.67	231.77

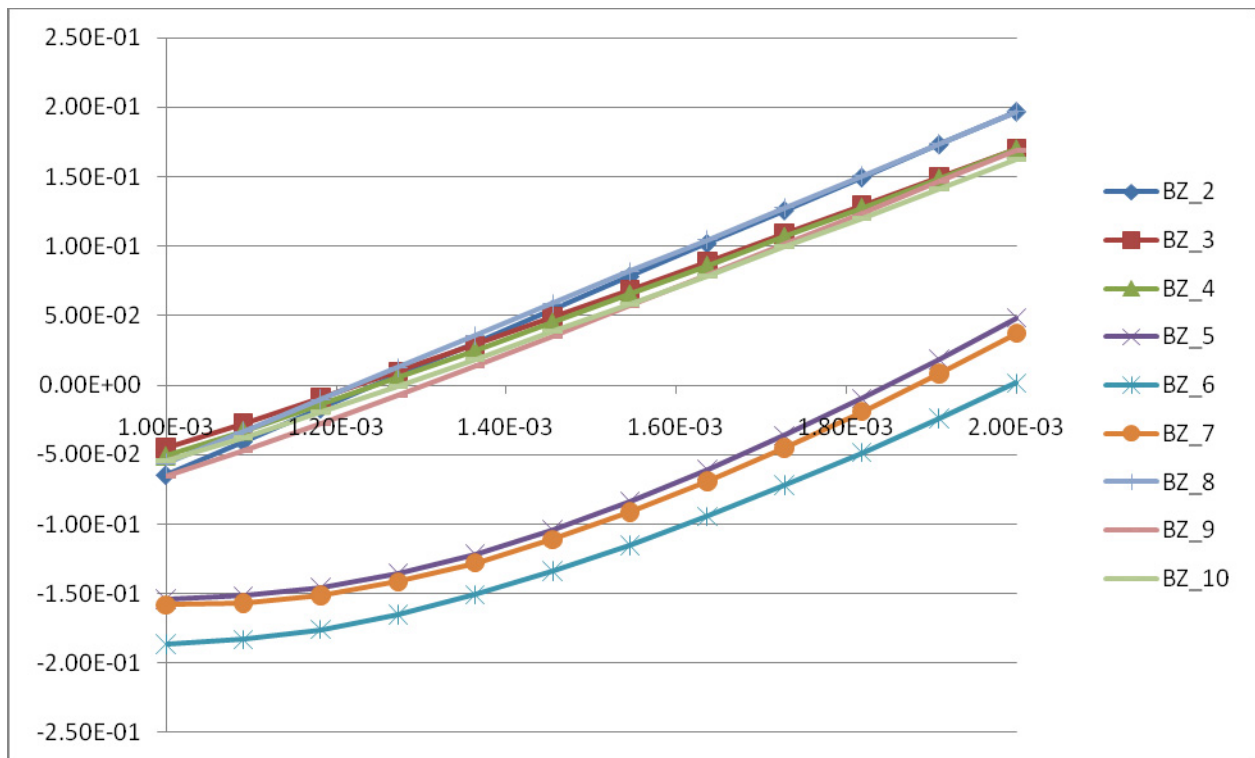


Figure 12: History plot of Bz (x axis—Time(s), y axis—B (Tesla), Plasma disrupts from 1ms to 2ms).

Figs. 13-16 plot the eddy current pattern in antenna, Faraday cage and vessel. Plasma disrupts from 1ms to 2ms.

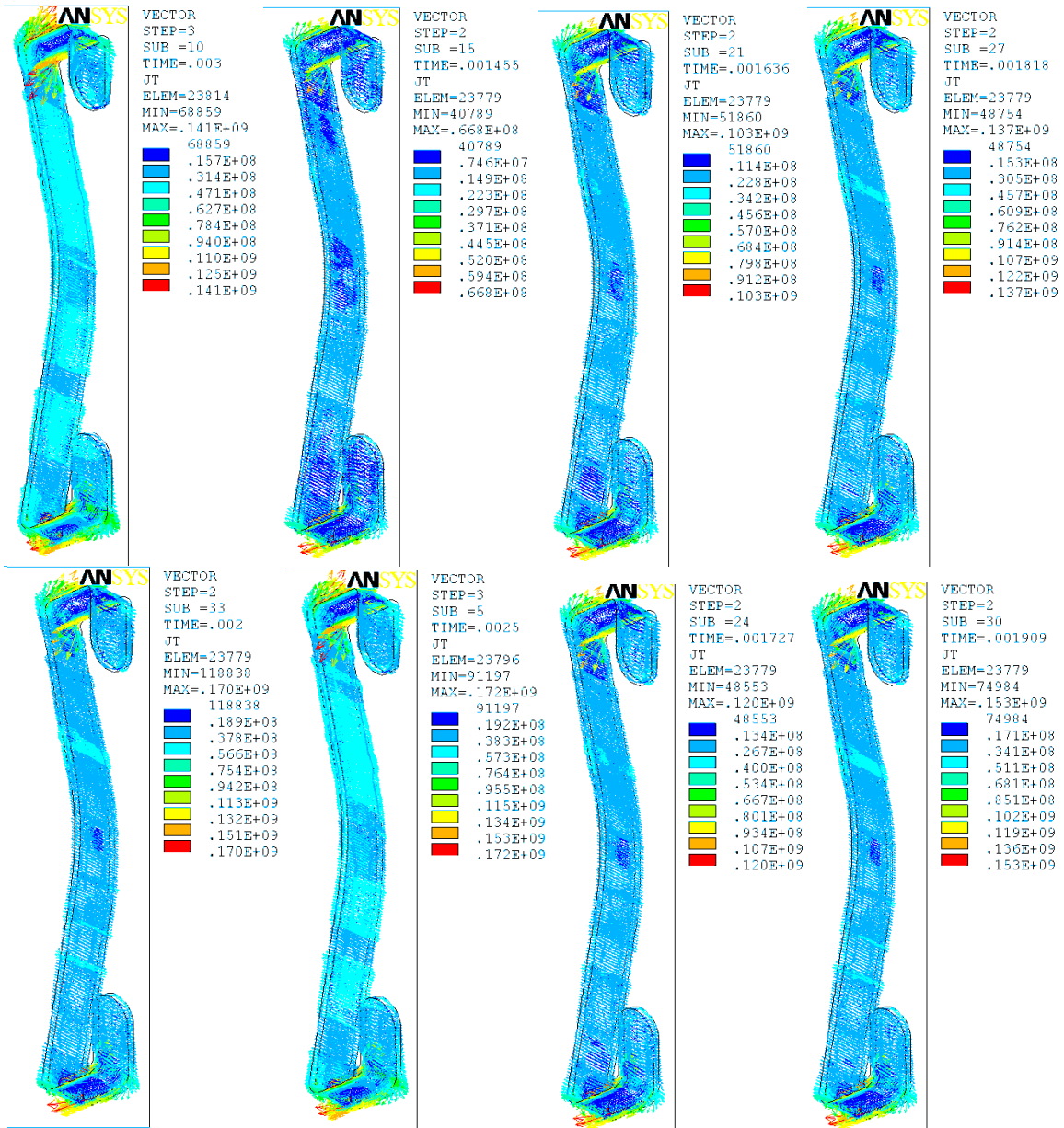


Figure 13: Eddy current pattern in antenna (A/m^2).

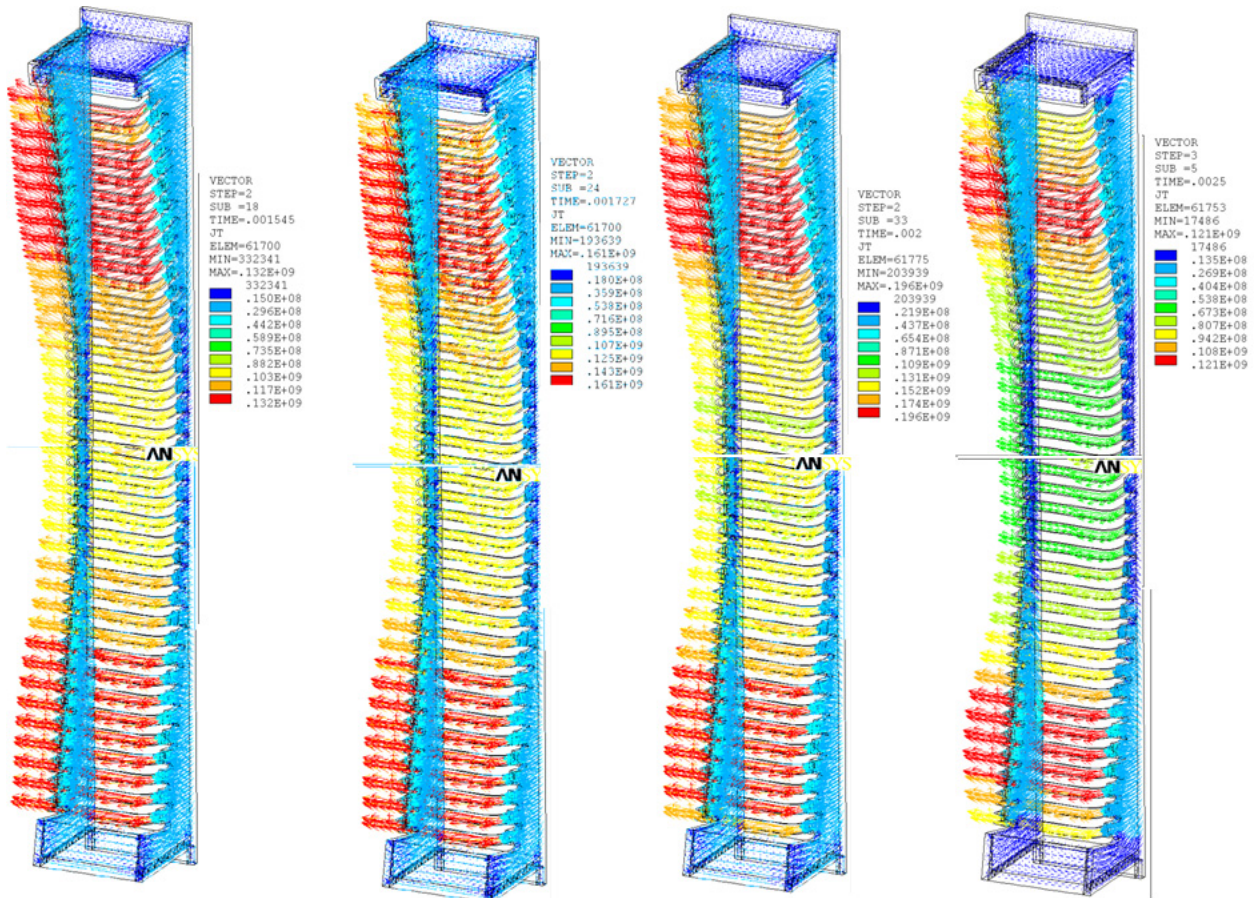


Figure 14: Eddy current pattern in Faraday cage (A/m^2).

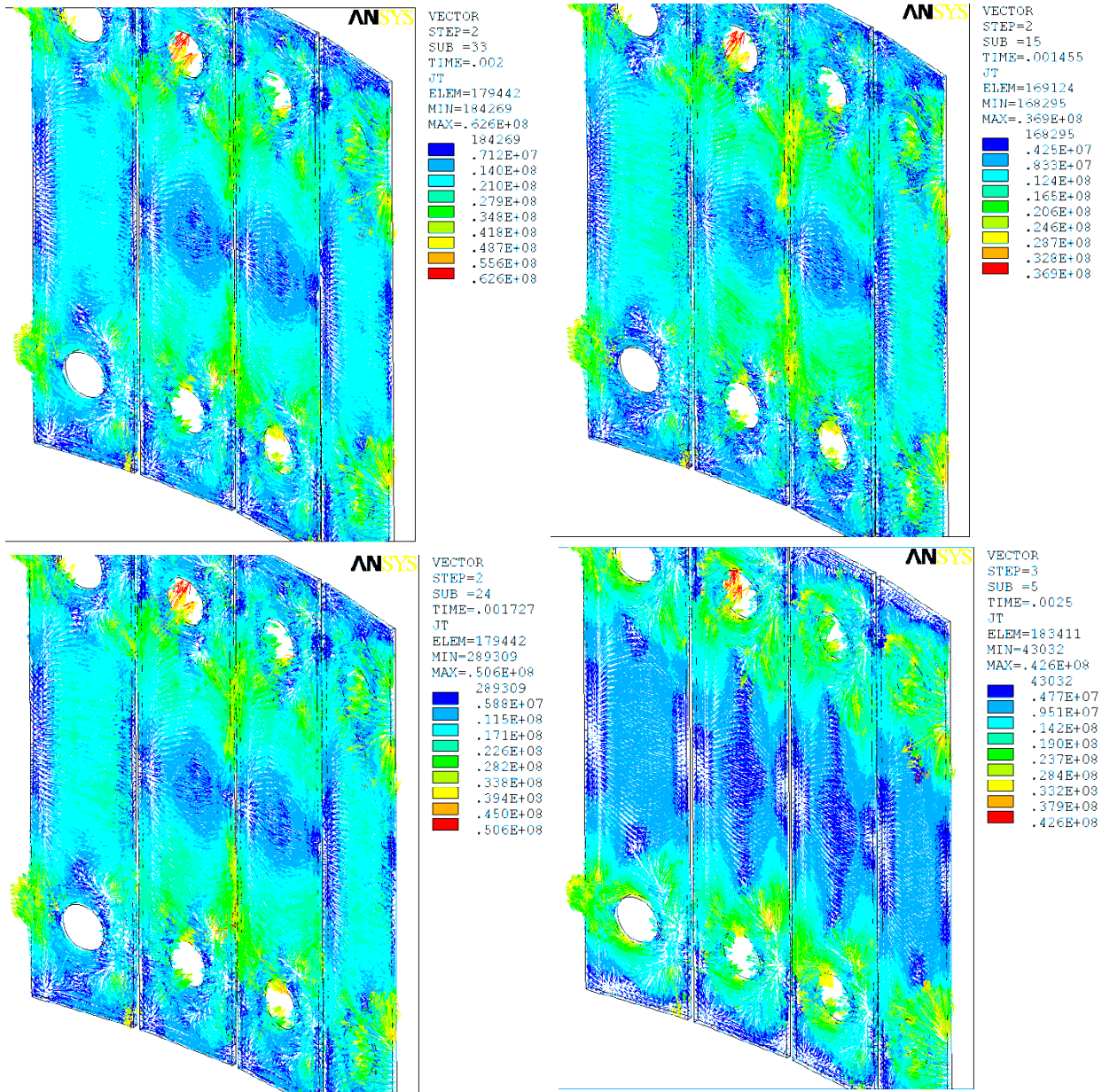


Figure 15: Eddy current pattern in the back plate of Faraday cage (A/m^2).

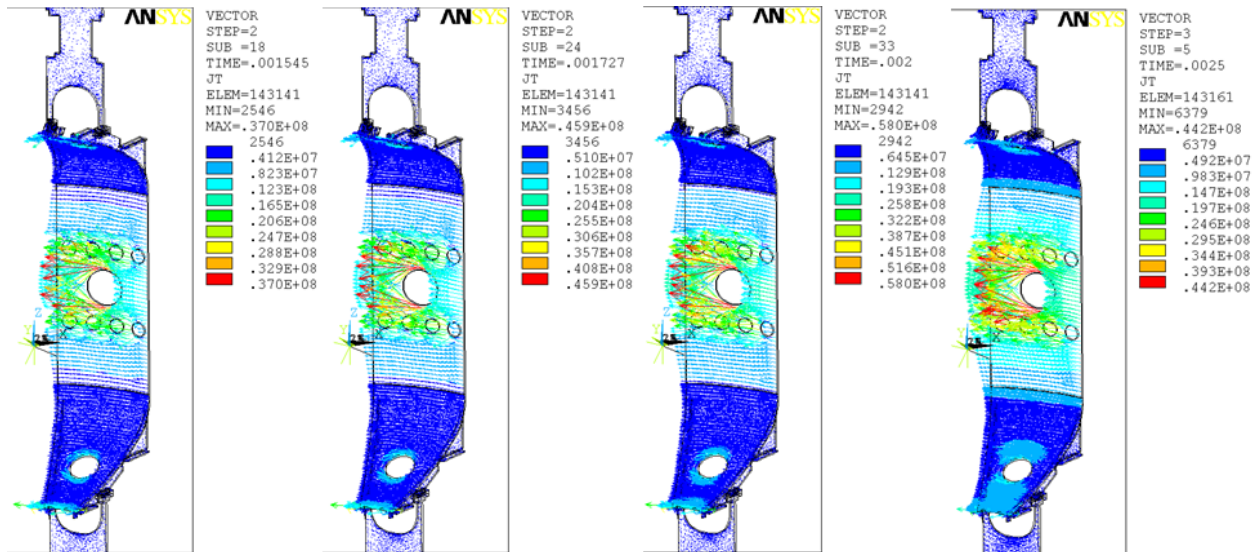


Figure 16: Eddy current pattern in the vessel (A/m²).

With NSTX upgrade, at the position of antenna there is a background field of $B_{\text{vertical}}=0.65$ T and $B_{\text{toroidal}}=0.56$ T. They won't induce eddy current but they produce Lorentz force to the components with currents. Because the eddy currents reach maximum at 1ms (the end of disruption), background field is added at this time point to calculate Lorentz force and then transfer the force data to the structural model for static run. The structural model is mainly same as EM model but air is removed and some structural connections are added. As described previously, the antenna, Faraday cage and vessel have some structural connections that are hard to be included in this model. These components include ceramic plug assembly, stainless steel flanges, conductors, bellows and ceramic insulations (Figure 17). But the loads on them need to be extracted from the model and then transfer to the detailed models or calculations for qualification. So in the structural model, some simple beams are added to simulate these fixtures and the loads are extracted.

See Figure 18, at 1ms (end of disruption), displacement of antenna is within 0.6 mm and maximal Von Mises stress is in the strips of Faraday cage, 155 MPa (22.5ksi). Searching from literatures, the tensile strength of Molybdenum is from 560 ~ 1150 MPa. So this stress is within allowable.

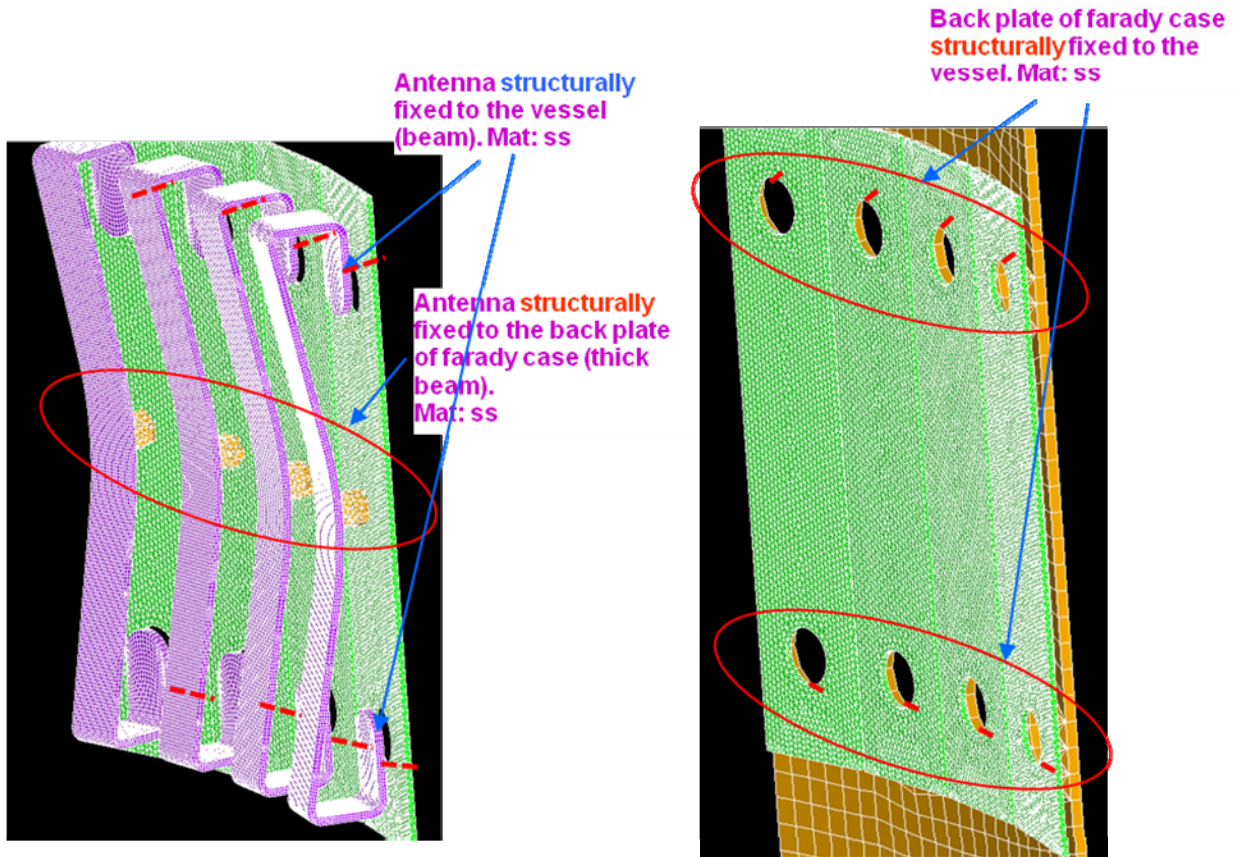


Figure 17: Structural connections are simplified in the model.

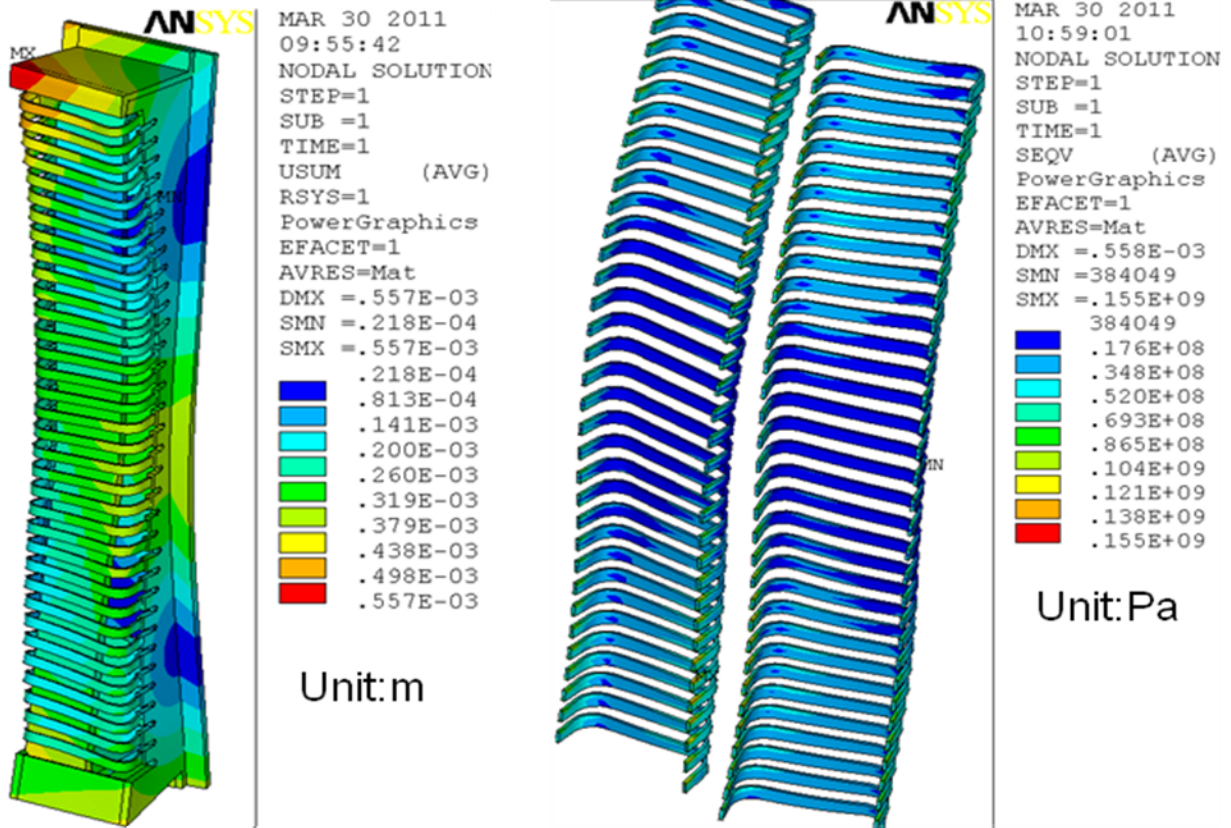


Figure 18: Displacement and Von Mises stress in antenna.

To simulate the fixtures, a beam element is used to connect the nodes at different components, e.g. a node at the antenna connected to a node at the back plate of Faraday cage. Thus the beam orientation will depend on the two nodes' positions, which will be a little different from real fixture, and loads direction cannot be consistent with regular coordinate system, i.e. Cartesian or cylindrical. To clearly show the axial and normal components of the loads, Local coordinate system was built and the loads are lists in the local coordinate. Local system x axis is the axial direction of the beam, y axis parallel to horizontal plane and z perpendicular to x and y.

Figure 19~21 show the beam loads and local coordinate systems.

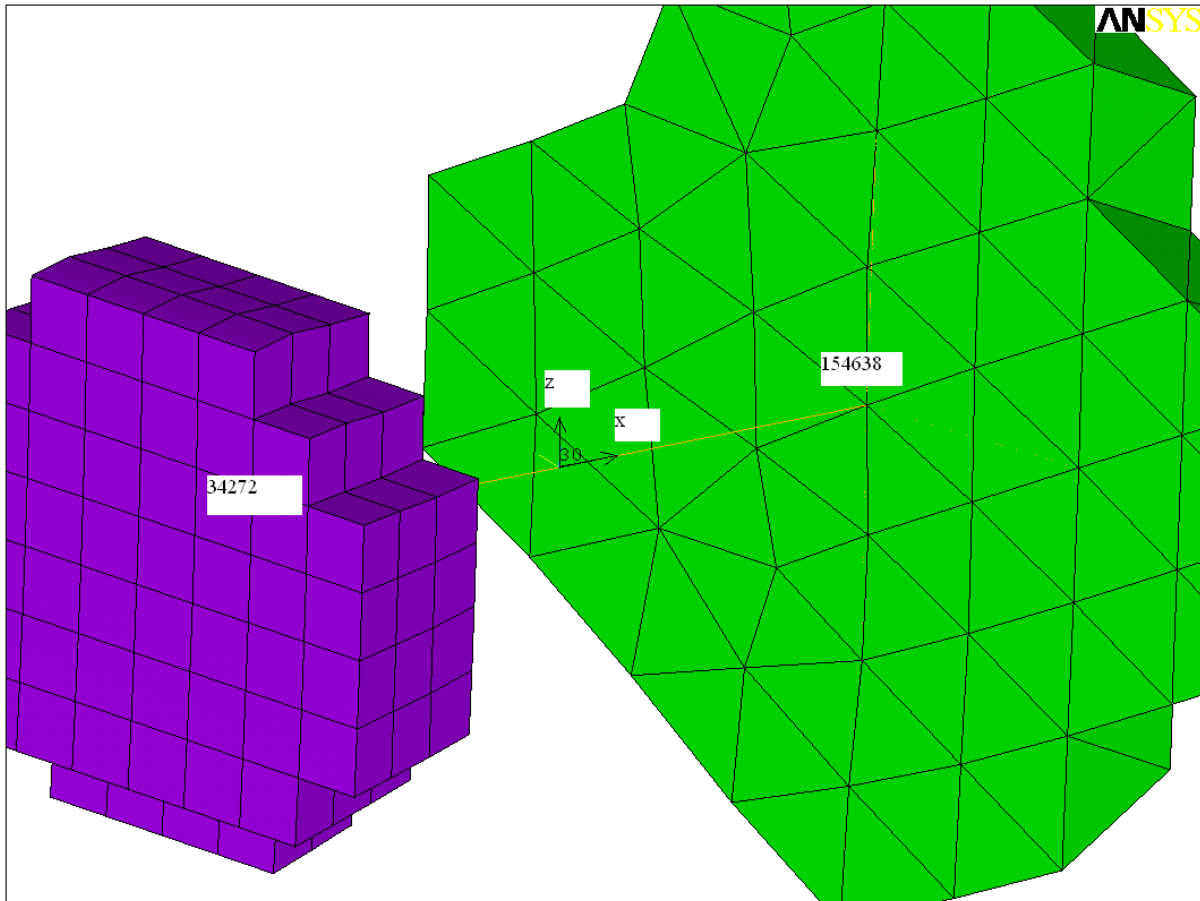


Figure 19: Beam connection between the middle of antenna and back plate of Faraday cage.

NODE	FX (N)	FY (N)	FZ (N)	MX (N-m)	MY (N-m)	MZ (N-m)
34272	-22.380	-3.4283	180.95	17.379	5.2062	2.2805
154638	22.476	3.4586	-180.70	-17.379	-14.640	-2.4569

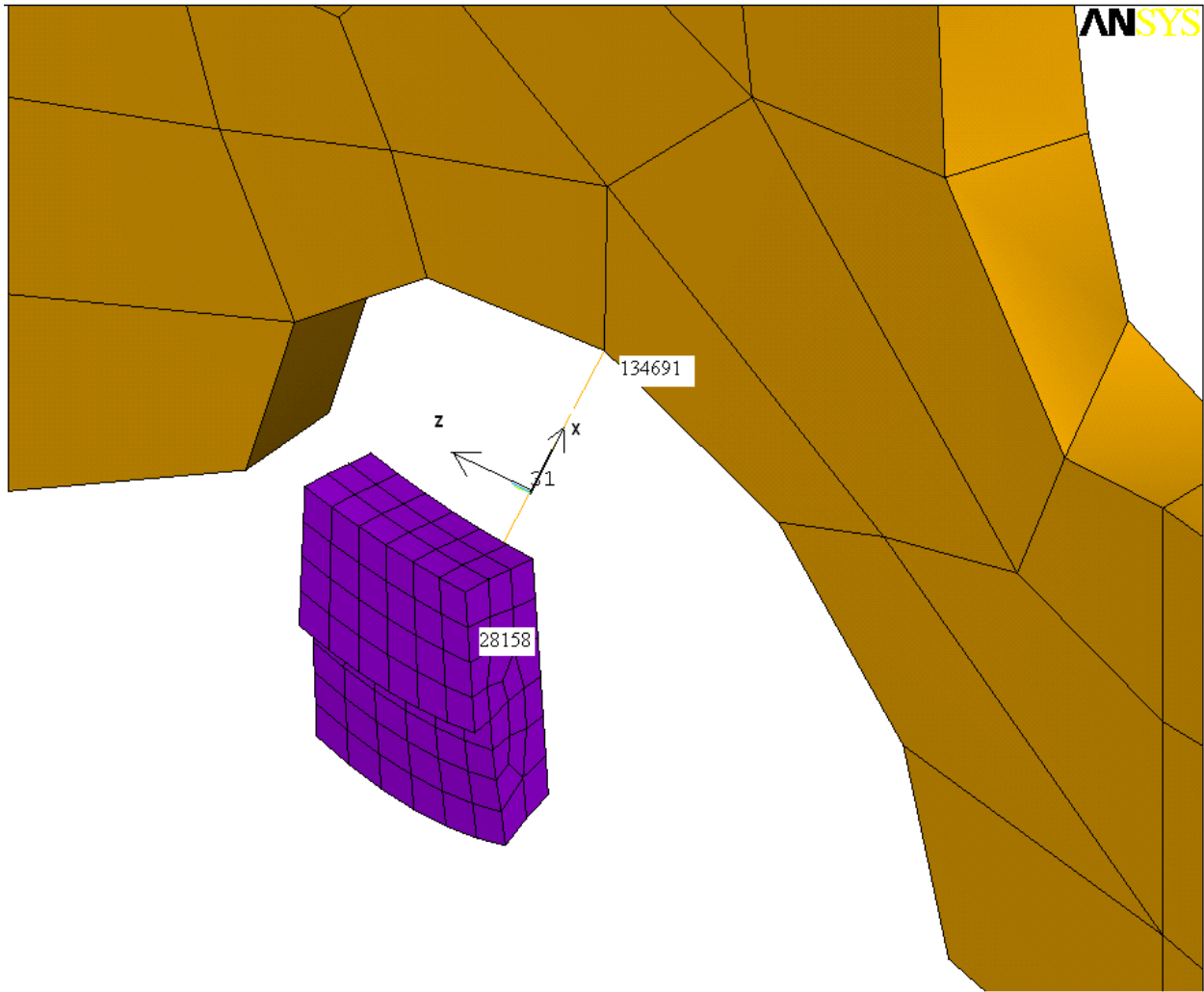


Figure 20: Beam connection between the end of antenna and vessel.

NODE	FX (N)	FY (N)	FZ (N)	MX (N-m)	MY (N-m)	MZ (N-m)
28158	-456.59	-100.76	144.26	43.229	-22.416	2.5311
134691	446.01	103.85	-143.27	-43.229	16.145	-6.9066

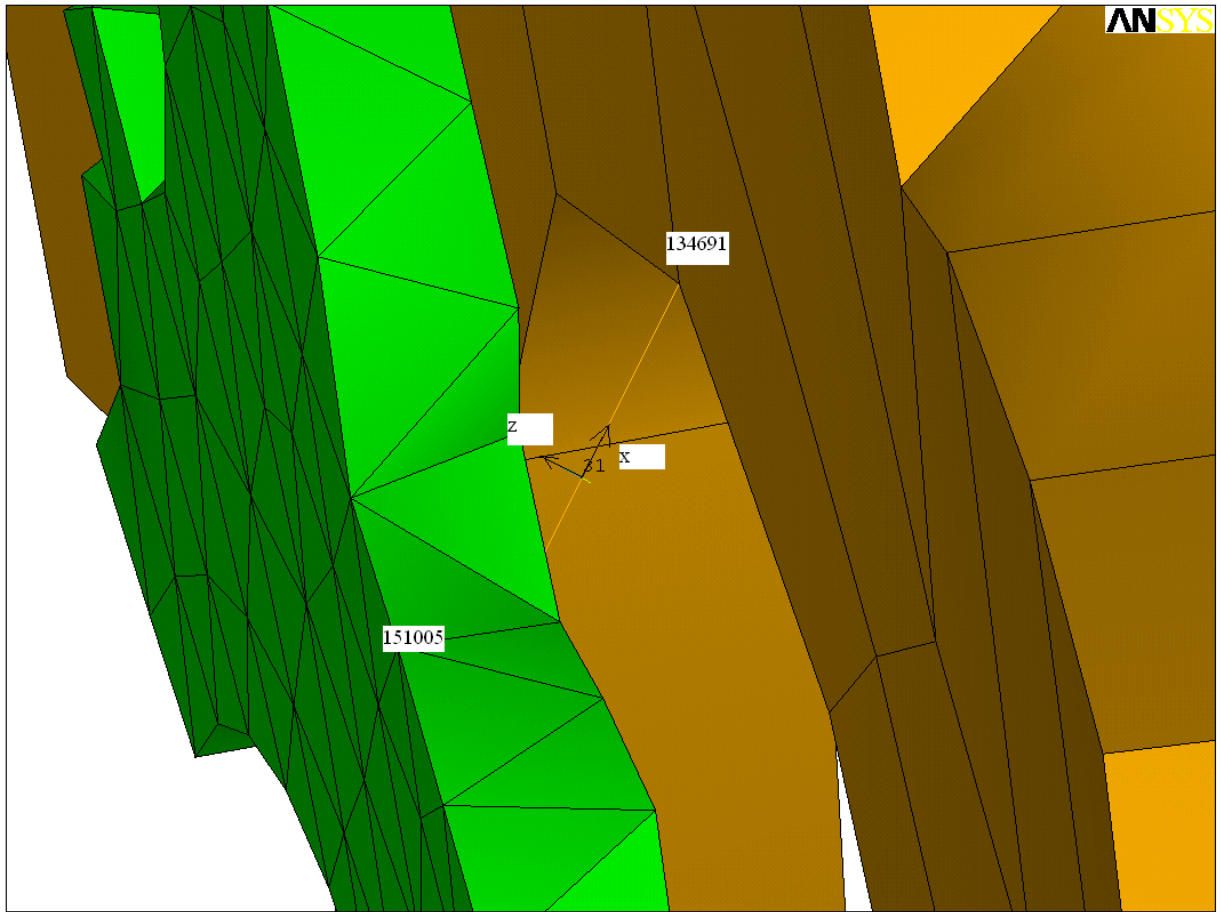


Figure 21: Beam connection between back plate of Faraday cage and vessel.

NODE	FX (N)	FY (N)	FZ (N)	MX (N-m)	MY (N-m)	MZ (N-m)
134691	6322.0	76.240	2460.1	-4.9614	-27.779	10.602
151005	-6334.7	-73.981	-2454.1	4.9614	79.724	-12.168